

**APPLICATION NOTE****File Access Control - Reading and Writing  
User Data in Alvium Flash Memory**V1.0.0  
2025-Jul-21**Table of contents**

Introduction .....	1
File access in Vimba X Viewer.....	2
Writing User Data .....	2
Reading User Data .....	5
File access with Vimba C++.....	5
Closing files .....	6
Opening User Data in Read Mode.....	7
Opening User Data in Write Mode.....	8
Deleting files .....	9
Reading out User Data.....	10
Writing User Data .....	12
Contact us .....	14
Website, email .....	14
Offices .....	14
Liability, trademarks, and copyright .....	14

**Introduction**

This application note gives a basic overview on how to use the File Access Control features to write and access User Data in the flash memory of Alvium cameras. The first focus will be using Vimba X Viewer, followed by C++ code using the Vimba X SDK.

## File access in Vimba X Viewer

### Writing User Data

Writing User Data to the flash memory will always append to the already written User Data. The write pointer cannot be changed, except if the file was deleted. In this example, there is no User Data in the flash memory yet, so the pointer is at 0. First, the features **FileOperationSelector**, **FileOpenMode** and **FileSelector** need to be set as shown in the screenshot.

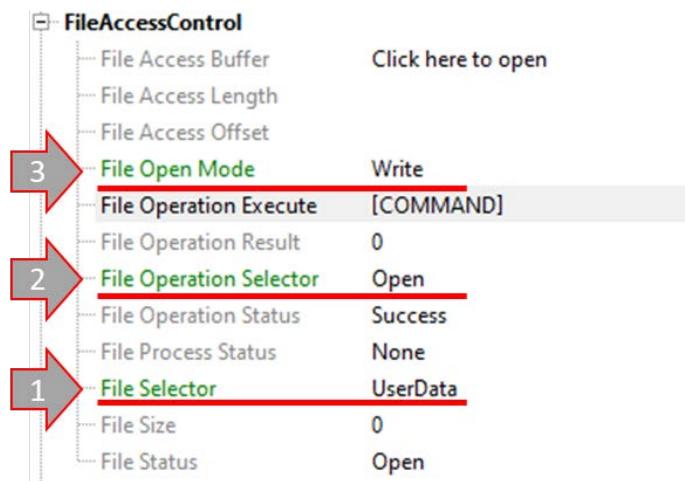


Figure 1 - Feature Selection for Write Operation

After completing these settings, the feature **FileOperationExecute** needs to be executed.

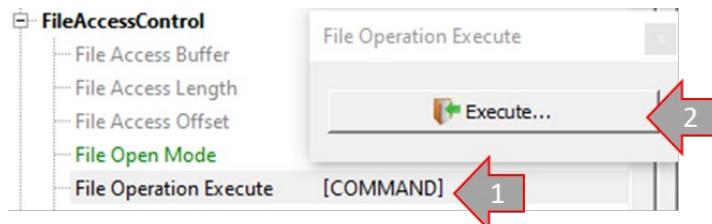


Figure 2 - Execute Command Feature "FileOperationExecute"

Now that the file is open for writing, the next operation to be selected in the **FileOperationSelector** is to Write to make the **FileAccessBuffer** accessible.

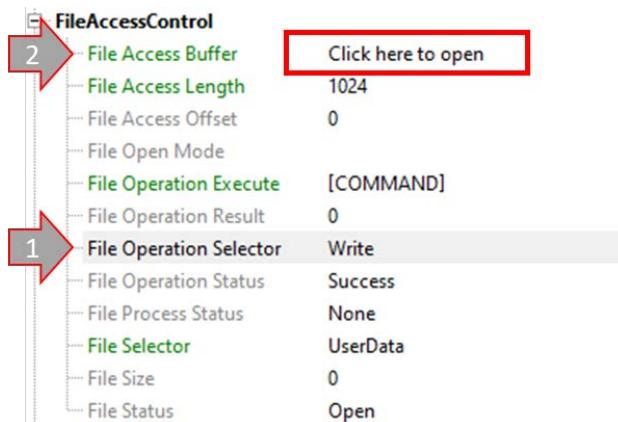


Figure 3 - Set FileOperationSelector to Write and open the FileAccessBuffer

Clicking on **Click here to open** opens the integrated Raw Data Editor, where you can see the HEX and ASCII values of the buffer. After editing the HEX values, click the save icon and close the buffer editor.

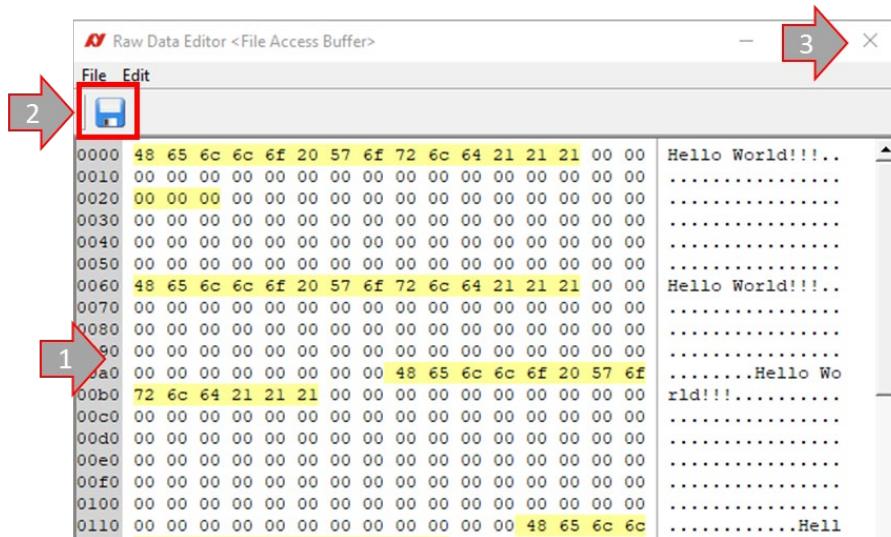


Figure 4 - Edit the Values of the FileAccessBuffer in the Raw Data Editor

Once the data in the buffer is complete, the buffer can be written into the camera memory. For that, after closing the Raw Data Editor, if none of the features have been changed in the meantime, only **FileOperationExecute** needs to be executed. If your data does not need the 1024 bytes of the buffer, you can limit the amount of buffer written into the camera, by editing **FileAccessLength**. Every ASCII sign should take up one byte, so for "Hello World!" your **FileAccessLength** should be 12.

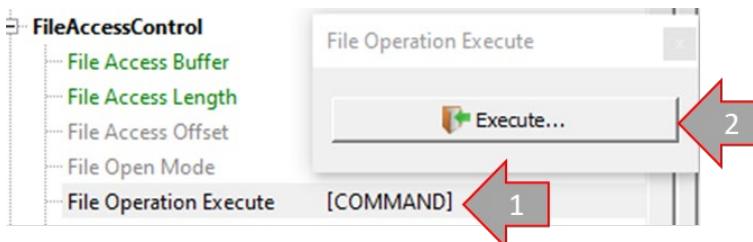


Figure 5 - Execute the Write Operation to write the Buffer into the Camera Memory

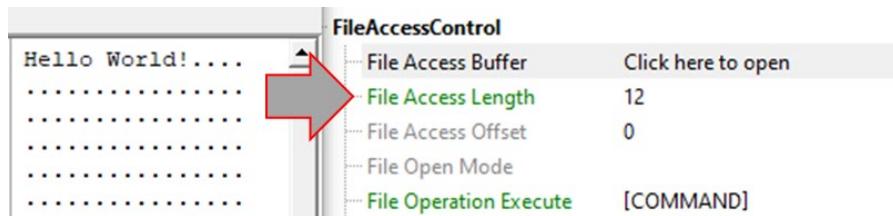


Figure 6 - For smaller Data, use FileAccessLength to only write the Amount needed

To check if the Write operation was successful, **FileOperationStatus** can be checked for *Success* and **FileSize** can be checked to see if the number matches the **FileAccessLength** plus the previous size and if **FileOperationResult** matches the **FileAccessLength**.

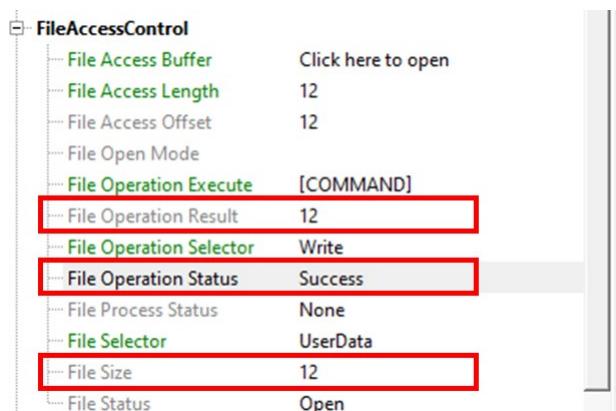


Figure 7 - Indicators to check if Write Operation was successful

**Note:** The write pointer can be reset only by deleting the file, power cycling the camera is not enough. If the file is not closed, the User Data is not saved into the camera.

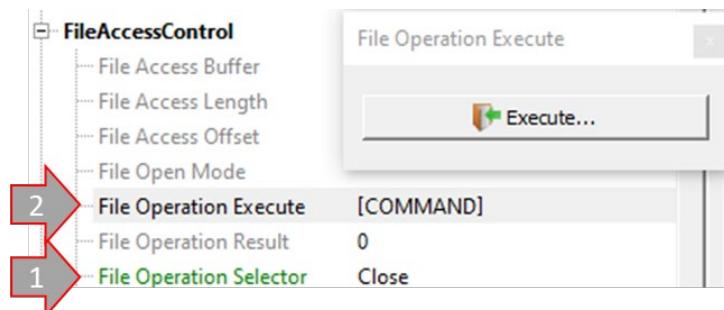


Figure 8 - If the File is not closed, close it with these two Selections before reading it

## Reading User Data

If the **FileStatus** is not *Closed*, then close the file first, before opening it in Read mode. To do that select Close in the **FileOperationSelector** and execute the **FileOperationExecute** command. Now that the file is for sure closed, open it in Read mode, by selecting the following features and values as shown in the screenshot and executing the **FileOperationExecution** command.

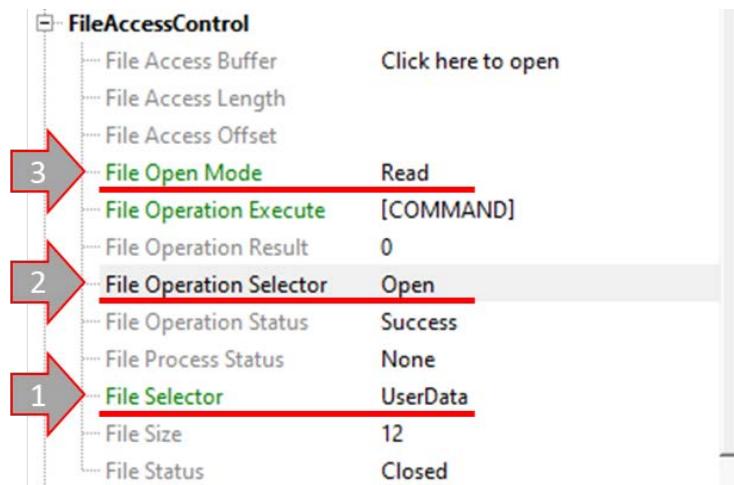


Figure 9 - Open UserData in Read Mode

Next, the opened file needs to be loaded into the **FileAccessBuffer** with a Read operation. Select Read for the **FileOperationSelector** feature and execute the **FileOperationExecution** command. Clicking to open the Raw Data Editor will now show the User Data that was loaded from the camera.

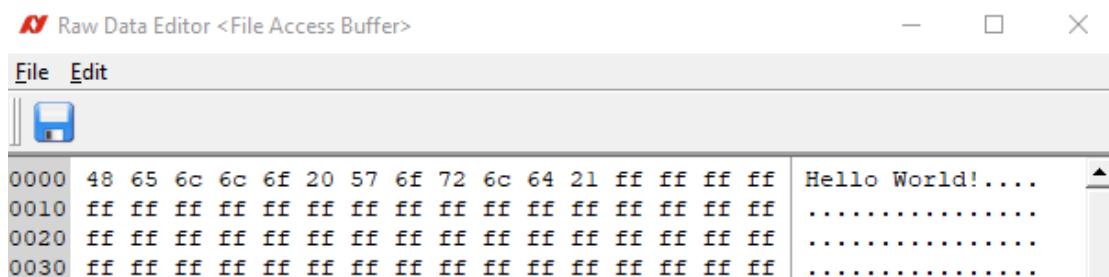


Figure 10 - UserData is successfully read out from the Camera Flash Memory

## File access with Vimba C++

Of course, Vimba C++ SDK uses the same features as shown in the GUI of the Vimba X Viewer, so this section is to summarize possible implementations of functions that close, open, read, write and delete User Data from the camera flash memory. If you would like to see the example program that these code snippets are based on, please contact [support@alliedvision.com](mailto:support@alliedvision.com). The example is named `UserData_FileAccess.cpp`.

## Closing files

To do anything with the files, it is important to open them in the right mode. Therefore, any function that opens the file should first check that it is closed and close it if necessary. It is also best practice to close the file after each write and read action to make sure that the file was written correctly in case of a program crash or the camera being physically disconnected and that there is no confusion about the state of the file.

```
void close_file(CameraPtr cam){  
    VmbError_t err;  
    FeaturePtr pFeature;  
    string stringVal;  
    // Check if the file is closed  
    cam->GetFeatureByName("FileStatus", pFeature);  
    err = pFeature->GetValue(stringVal);  
    if (stringVal == "Closed") {  
        cout << "File is already closed." << endl;  
    }  
    else {  
        cam->GetFeatureByName("FileOperationSelector", pFeature);  
        err = pFeature->SetValue("Close"); // Select "Close" as operation  
        cam->GetFeatureByName("FileOperationExecute", pFeature);  
        err = pFeature->RunCommand(); // Execute the selected operation  
    }  
}
```

## Opening User Data in Read Mode

The file can only be opened if it is not already opened. Therefore, it is important to check for the file status before trying to open it, to ensure that the right file is opened in the right mode.

```
Void open_UserData_r(CameraPtr cam){  
    VmbError_t err;  
    cam->GetFeatureByName("FileSelector", pFeature);  
    err = pFeature->SetValue("UserData"); // Select UserData file  
    // Check if selected file is opened, if yes close file  
    cam->GetFeatureByName("FileStatus", pFeature);  
    err = pFeature->GetValue(stringVal);  
    if (stringVal == "Open") {  
        close_file(cam);  
    }
```

```
    cam->GetFeatureByName("FileOperationSelector", pFeature);  
    err = pFeature->SetValue("Open"); // Select "Open" as operation  
    cam->GetFeatureByName("FileOpenMode", pFeature);  
    err = pFeature->SetValue("Read"); // Select "Read" as mode  
    cam->GetFeatureByName("FileOperationExecute", pFeature);  
    err = pFeature->RunCommand(); // Execute the selected operation  
}
```

## Opening User Data in Write Mode

```
void open_UserData_w(CameraPtr cam){  
    VmbError_t err;  
    FeaturePtr pFeature;  
    string stringVal;  
    cam->GetFeatureByName("FileSelector", pFeature);  
    err = pFeature->SetValue("UserData"); // Select UserData file  
    // Check if selected file is opened, if yes close file  
    cam->GetFeatureByName("FileStatus", pFeature);  
    err = pFeature->GetValue(stringVal);  
    if (stringVal == "Open") {  
        close_file(cam);  
    }  
    cam->GetFeatureByName("FileOperationSelector", pFeature);  
    err = pFeature->SetValue("Open"); // Select "Open" as operation  
    cam->GetFeatureByName("FileOpenMode", pFeature);  
    err = pFeature->SetValue("Write"); // Select "Write" as mode  
    cam->GetFeatureByName("FileOperationExecute", pFeature);  
    err = pFeature->RunCommand(); // Execute the selected operation  
}
```

## Deleting files

```
void delete_file(CameraPtr cam) {
    VmbError_t err = 0;
    FeaturePtr pFeature;
    string stringVal;
    VmbInt64_t nFileSize = 0;
    err = close_file(cam); // Close file before deleting
    cam->GetFeatureByName("FileStatus", pFeature);
    err = pFeature->GetValue(stringVal);
    if (stringVal == "Closed") { // Check if FileStatus is "Closed"
        cam->GetFeatureByName("FileOperationSelector", pFeature);
        err = pFeature->SetValue("Delete"); // Select "Delete" as mode
        cam->GetFeatureByName("FileOperationExecute", pFeature);
        err = pFeature->RunCommand(); // Execute the selected operation
        cam->GetFeatureByName("FileSize", pFeature);
        pFeature->GetValue(nFileSize);
        if (nFileSize == 0) { // Check if FileSize is 0
            cout << "File deleted." << endl;
        }
        else {
            cout << "Delete error: File size is not zero." << endl;
        }
    }
    else {
        cout << "Delete error: File was not closed successfully." << endl;
    }
}
```

## Reading out User Data

The size of the file access buffer is only 1024 bytes maximum. So, if the file size of the User Data is larger than that, the file needs to be read out in several steps. This can be done by editing the feature `FileAccessOffset`. For example: First read out the first 1024 bytes and save it into a variable. Then set `FileAccessOffset` to 1024, read out more of the file and add it to your existing variable. This example code does not take larger file sizes into account, but that can be changed easily by for example making the offset an argument of the function.

```
UcharVector read_UserData(CameraPtr cam){  
    VmbError_t err;  
    FeaturePtr pFeature;  
    UcharVector UserData;  
    VmbInt64_t nFileSize = 0;  
    string stringVal;  
    err = open_UserData_r(cam); // Open file in read mode  
    cam->GetFeatureByName("FileSize", pFeature);  
    pFeature->GetValue(nFileSize); // Check file size  
    if (nFileSize > 0) {  
        cam->GetFeatureByName("FileOperationSelector", pFeature);  
        err = pFeature->SetValue("Read"); // Select "Read" as operation  
        cam->GetFeatureByName("FileAccessLength", pFeature);  
        // Set file access length depending on file size  
        if (nFileSize > 1024)  
        {  
            pFeature->SetValue(1024);  
        }  
        else {  
            pFeature->SetValue(nFileSize);  
        }  
        cam->GetFeatureByName("FileAccessOffset", pFeature);  
        pFeature->SetValue(0); // Select 0 as file access offset  
        cam->GetFeatureByName("FileOperationExecute", pFeature);  
        err = pFeature->RunCommand(); // Execute the selected operation  
        cam->GetFeatureByName("FileOperationStatus", pFeature);  
        pFeature->GetValue(stringVal);  
        if (stringVal == "Success"){ // Check for read success  
            cam->GetFeatureByName("FileAccessBuffer", pFeature);  
        }  
    }  
}
```

```
// Read out buffer into variable UserData
    pFeature->GetValue(UserData);
}
}
else {
    cout << "Can't read UserData, file size is 0." << endl;
}
close_file(cam); // Close file after reading -> good practice
return UserData;
}

int main(){
...
UcharVector file_access_buffer;
file_access_buffer = read_UserData(cam);
for (int i = 0; i < file_access_buffer.size(); i++){
    cout << file_access_buffer[i];
...
}
```

## Writing User Data

By default, the write operation will append the data in the file access buffer to the existing data. Modifying the data can only be achieved by reading it out, modifying it, deleting the old file, and writing the modified file on the camera. This example includes an argument to differentiate between add and overwrite.

```
UcharVector write_UserData(CameraPtr cam, UcharVector UserData,
                           bool overwrite = false) {
    VmbError_t err;
    FeaturePtr pFeature;
    VmbInt64_t nFileSize = 0;

    VmbInt64_t nDataSize = 0;
    string stringVal;
    nDataSize = UserData.size();
    if (nDataSize > 0)
    {
        // Overwrite current file on camera
        if (overwrite == true) {
            err = delete_file(cam); // Closes and deletes file
            err = open_UserData_w(cam); // Open file in write mode
            cam->GetFeatureByName("FileOperationSelector", pFeature);
            err = pFeature->SetValue("Write"); // Select "Write"
            cam->GetFeatureByName("FileAccessLength", pFeature);
            // Write only as much memory, as needed for data (recommended)
            err = pFeature->SetValue(nDataSize);
            cam->GetFeatureByName("FileAccessBuffer", pFeature);
            err = pFeature->SetValue(UserData); // Load into buffer
            cam->GetFeatureByName("FileOperationExecute", pFeature);
            err = pFeature->RunCommand(); // Execute write operation
            // Optional: Check file size for successful write
            cam->GetFeatureByName("FileSize", pFeature);
            pFeature->GetValue(nFileSize);
        }
        else {
            // Add to current file on camera
            err = close_file(cam);
            err = open_UserData_w(cam); // Open file in write mode
            cam->GetFeatureByName("FileOperationSelector", pFeature);
        }
    }
}
```

```
    err = pFeature->SetValue("Write"); // Select "Write"
    cam->GetFeatureByName("FileAccessLength", pFeature);
    err = pFeature->SetValue(nDataSize);
    cam->GetFeatureByName("FileAccessBuffer", pFeature);
    // Write only as much memory, as needed for data (recommended)
    err = pFeature->SetValue(UserData);
```

```
    cam->GetFeatureByName("FileOperationExecute", pFeature);
    err = pFeature->RunCommand(); // Execute write operation
}
}
else {
    cout << "Data is empty, no data was written." << endl;
}
close_file(cam); // Close file after writing -> necessary!
return UserData;
}
int main(){
...
// Write data in ASCII as string, to be formatted into UcharVector
string stringBaseData = "Hello World!!!!!!!!!!!!!!";
UcharVector new_UserData;
VmbUchar_t temp;
// Separate string into VmbUchar and stack them into a UcharVector
for (int i = 0; i < stringBaseData.length(); i++){
    temp = (VmbUchar_t)stringBaseData[i];
    new_UserData.push_back(temp);
}
write_UserData(cam, new_UserData, true); // Write new data into camera
...
}
```

## Contact us

### Website, email

#### General

[www.alliedvision.com/en/contact](http://www.alliedvision.com/en/contact)

[info@alliedvision.com](mailto:info@alliedvision.com)

#### Distribution partners

[www.alliedvision.com/en/avt-locations/avt-distributors](http://www.alliedvision.com/en/avt-locations/avt-distributors)

#### Support

[www.alliedvision.com/en/support](http://www.alliedvision.com/en/support)

[www.alliedvision.com/en/about-us/contact-us/technical-support-repair-/rma](http://www.alliedvision.com/en/about-us/contact-us/technical-support-repair-/rma)

## Offices

### Europe, Middle East, and Africa (Headquarters)

Allied Vision Technologies GmbH

Taschenweg 2a

07646 Stadtdroda, Germany

T// +49 36428 677-0 (Reception)

T// +49 36428 677-230 (Sales)

F// +49 36428 677-28

### North, Central, and South America, Canada

Allied Vision Technologies Canada Inc.

300 – 4621 Canada Way

Burnaby, BC V5G 4X8, Canada

T// +1 604 875 8855

### Asia-Pacific | China

Allied Vision Technologies Shanghai Co Ltd.

B-510, Venture International Business Park

2679 Hechuan Road

Minhang District, Shanghai 201103

People's Republic of China

T// +86 21 64861133

### USA

Allied Vision Technologies, Inc.

102 Pickering Way - Suite 502

Exton, PA 19341, USA

Toll-free// +1-877-USA-1394

T// +1 978 225 2030

### Singapore

Allied Vision Technologies Asia Pte. Ltd

82 Playfair Rd, #07-01 D'Lithium

Singapore 368001

T// +65 6634 9027

### Japan

Allied Vision Technologies

Yokohama Portside Bldg. 10F

8-1 Sakaé-cho, Kanagawa-ku

Yokohama-shi, Kanagawa, 221-0052

T// +81 (0) 45 577 9527

## Liability, trademarks, and copyright

Allied Vision has tested the product under the described conditions. The customer assumes all risk of product damage, application compromise or potential failure, and Sales Warranty loss related to deviation from the described conditions. Allied Vision's acknowledgement of such deviations in the customer's modified product or applications does not constitute advice for use. No Warranty is offered or implied by Allied Vision regarding the customer's assumed risk or legal responsibilities with such modified products or applications.

All text, pictures, and graphics are protected by copyright and other laws protecting intellectual property. All content is subject to change without notice. All trademarks, logos, and brands cited in this document are property and/or copyright material of their respective owners. Use of these trademarks, logos, and brands does not imply endorsement.

Copyright © 2025 Allied Vision Technologies GmbH. All rights reserved.